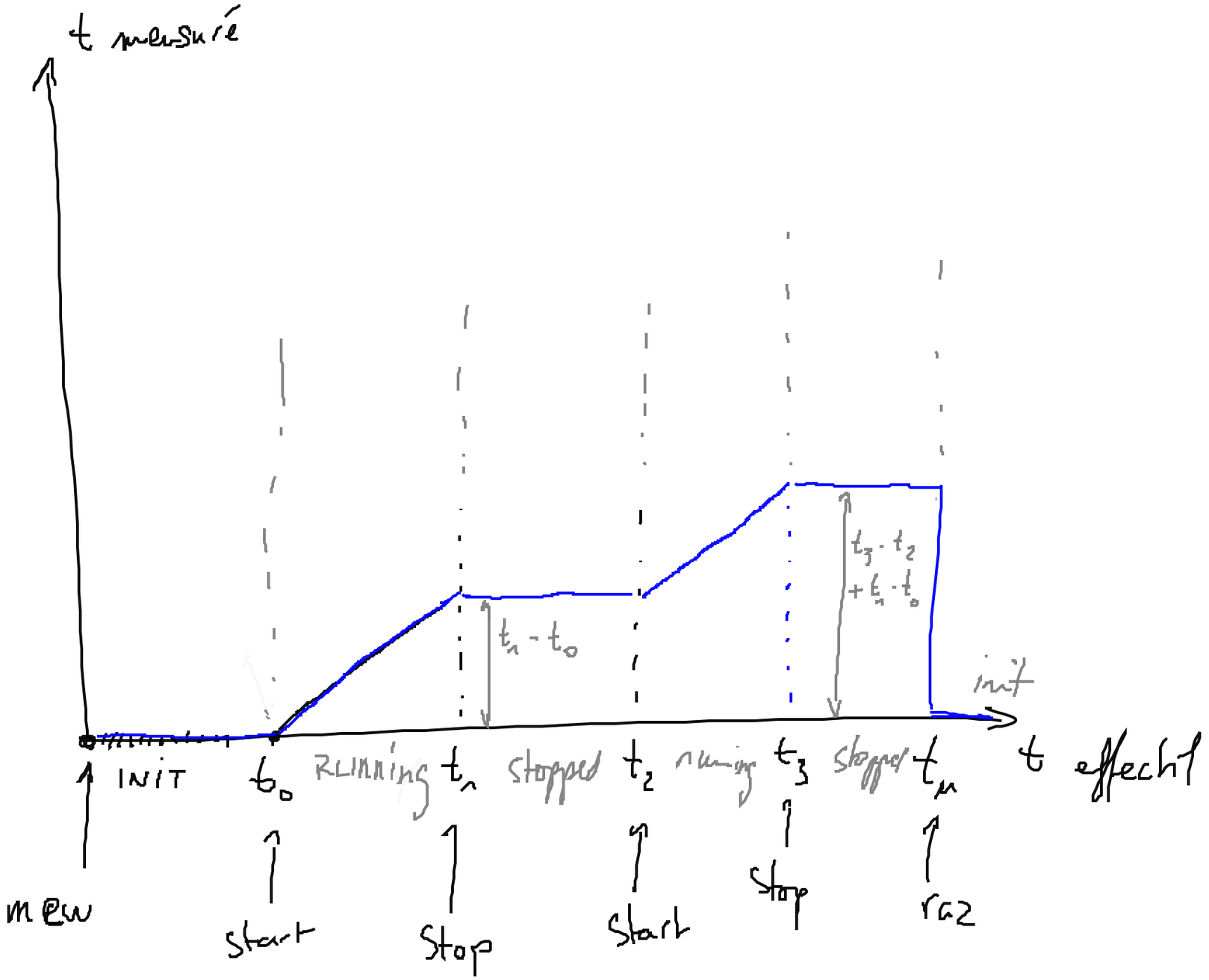
t mesuré
t effectif
INIT
t_0
RUNNING
t_1
stopped
t_2
running
t_3
stopped
t_4
$t_1 - t_0$
$t_3 - t_2$
$+ t_1 - t_0$
init
mew
start
Stop
Start
Stop
raz